### Introduction to Data Structures

### Data Structures

 Data Structures A data structure is a scheme for organizing data in the memory of a computer. Some of the more commonly used data structures include lists, arrays, stacks, queues, heaps, trees, and graphs The way in which the data is organized affects the performance of a program for different tasks

## **Types of Data Structure**

- There are basically two types of data structure
- Linear Data Structure: Stack, Queue,Linked List
- Non-Linear Data Structure. Tree And Graph

## Stack

- Stack is a linear data structure which works on LIFO or FILO order i.e. First In Last Out or Last In First Out.
- In Stack element is always added at top of stack and also removed from top of the stack.
- Stack is useful in recursive function, function calling, mathematical expression, calculation, reversing the string etc.

## Queue

- Queue is also a linear data structure which work on FIFO order i.e. First In First Out.
- In queue element is always added at rear of queue and removed from front of queue.
- Queue applications are in CPU scheduling, Disk Scheduling, IO Buffers, pipes, file input output.

# Linked List

- A linked list is a linear collection of data elements, in which linear order is not given by their physical placement in memory.
- Elements may be added in front, end of list as well as middle of list.
- Linked list may use for dynamic implementation of stack and queue.

### Trees

- A tree is a non linear data structure. a root value and subtrees of children with a parent node, represented as a set of linked nodes. Nodes can be added at any different node. Tree applications includes:-
- Manipulate hierarchical data.
- Make information easy to search (see tree traversal).
- Manipulate sorted lists of data.
- As a workflow for compositing digital images for visual effects.
- Router algorithms

# Graphs

- A graph is a non linear data structure. A set of items connected by edges. Each item is called a vertex or node.
- Formally, a graph is a set of vertices and a binary relation between vertices, adjacency.
- Graph applications:- finding shortest routes, searching, social network connections, internet routing.

### Trees

- Length of a path = number of edges
- Depth of a node N = length of path from root to N
- Height of node N = length of longest path from N to a leaf
- Depth and height of tree = height of root



## Definition

A tree is a set of nodes that is

a. an empty set of nodes, or

b. has one node called the root from which zero or more trees (sub trees) descend.

## Implementation of Trees

• Obvious Pointer-Based Implementation: Node with value and pointers to children



### 1<sup>st</sup> Child/Next Sibling Representation

• Each node has 2 pointers: one to its first child and one to next sibling



# Application: Arithmetic Expression Trees

Example Arithmetic Expression:

A + (B \* (C / D) )

Tree for the above expression:

- Used in most compilers
- No parenthesis need use tree structure
- Can speed up calculations e.g. replace
   / node with C/D if C and D are known
- Calculate by traversing tree (how?)



## **Traversing Trees**

- Preorder: Root, then Children
   + A \* B / C D
- Postorder: Children, then Root
   A B C D / \* +
- Inorder: Left child, Root, Right child
   A + B \* C / D



## **Binary Trees**

Α

G

Н

В

**∖**D

#### • Properties

Notation:

depth(tree) = MAX {depth(leaf)} = height(root)

- $\max \# of leaves = 2^{depth(tree)}$
- max # of nodes =  $2^{depth(tree)+1} 1$
- max depth = n-1
- average depth for n nodes =  $\sqrt{n}$ (over all possible binary trees)
- Representation:

Data	
left	right
pointer	pointer

# Binary Search Tree Dictionary Data Structure

- Search tree property
  - all keys in left subtree smaller than root's key
  - all keys in right subtree larger than root's key
  - result:
    - easy to find any given key
    - inserts/deletes by changing links



## In Order Listing



visit left subtree visit node visit right subtree

In order listing:  $2 \rightarrow 5 \rightarrow 7 \rightarrow 9 \rightarrow 10 \rightarrow 15 \rightarrow 17 \rightarrow 20 \rightarrow 30$ 

## Finding a Node



```
Node find (Comparable x, Node
root)
if (root == NULL)
  return root;
else if (x < root.key)</pre>
  return find(x,root.left);
else if (x > root.key)
  return find(x, root.right);
else
  return root;
```

### Insert

Concept: proceed down tree as in Find; if new key not found, then insert a new node at last spot traversed

```
void insert(Comparable x, Node root) {
  // Does not work for empty tree - when root is
  NULL
  if (x < root.key) {
      if (root.left == NULL)
          root.left = new Node(x);
      else insert( x, root.left ); }
  else if (x > root.key) {
      if (root.right == NULL)
          root.right = new Node(x);
      else insert( x, root.right ); } }
```

## Time to Build a Tree

Suppose  $a_1, a_2, ..., a_n$  are inserted into an initially empty BST:

- 1.  $a_1, a_2, ..., a_n$  are in increasing order
- 2.  $a_1, a_2, ..., a_n$  are in decreasing order
- 3.  $a_1$  is the median of all,  $a_2$  is the median of elements less than  $a_1$ ,  $a_3$  is the median of elements greater than  $a_1$ , etc.
- 4. data is randomly ordered

# Analysis of BuildTree

- Increasing / Decreasing:  $\theta(n^2)$ 1+2+3+...+ $n = \theta(n^2)$
- Medians yields perfectly balanced tree θ(n log n)
- Average case assuming all input sequences are equally likely is  $\theta(n \log n)$ 
  - equivalently: average depth of a node is log n Total time = sum of depths of nodes



### Successor



### **Deletion - Leaf Case**



### **Deletion - One Child Case**



## **Deletion - Two Child Case**



replace node with value guaranteed to be between the left and right subtrees: the successor

## **Deletion - Two Child Case**



always easy to delete the successor – always has either 0 or 1 children!

## **Deletion - Two Child Case**



Finally copy data value from deleted successor into original node